

Data analysis – What data and what to look for?

Input: Real-world data from mobile networks (e.g. CRAWDAD datasets)

Question: Can we detect basic temporal features?



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Examples of properties (seen previously):

1. $\mathcal{J}^{1\forall}$: At least one node can reach all the others through a journey ($1 \rightsquigarrow *$),
2. \mathcal{TC} : All nodes can reach each other through journeys ($* \rightsquigarrow *$),
3. $\mathcal{E}^{1\forall}$: At least one node shares at some point an edge with every other ($1 - *$),
4. \mathcal{K} : All pairs of nodes share at some point an edge ($* - *$),
5. $\mathcal{J}^{\forall 1}$: At least one node can be reached by all others through a journey ($* \rightsquigarrow 1$),
6. $\mathcal{J}^{1\forall>}$: At least one node can reach all the others through a strict journey ($1 \rightsquigarrow^{st} *$),
7. $\mathcal{TC}^>$: All nodes can reach each other through strict journeys ($* \rightsquigarrow^{st} *$).

Data analysis – Defining intermediate objects

Input: $\mathcal{G} = \{G_1, \dots, G_k\}$, with $G_i = (V, E_i)$.

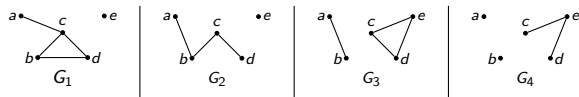
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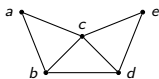
(1) The footprint

The *footprint* of \mathcal{G} is the (static) graph $G = (V, E)$ such that $E = \cup_i E_i$. Here, we can assume that V_i does not vary.

For example: this temporal graph...



... has footprint



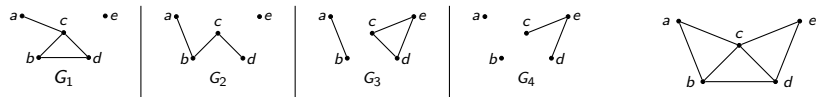
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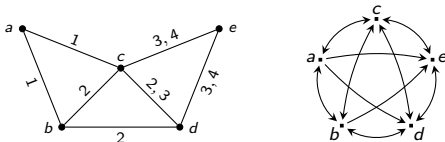


(2) The transitive closure of journeys

The *transitive closure* of the journeys is the directed graph $\vec{G} = (V, \vec{E})$ such that $(u, v) \in \vec{E}$ if and only if there is a journey from u to v in \mathcal{G} . We distinguish between *strict* and *non-strict* transitive closures, depending on the type of journeys allowed.

For example, this temporal graph...

...has strict transitive closure



Data analysis – Using the intermediate objects

Now, we have the following equivalences:

- ▶ $\mathcal{J}^{1\forall} \iff$ The transitive closure contains an out-dominating set of size 1.
- ▶ $\mathcal{J}^{\forall 1} \iff$ The transitive closure contains an in-dominating set of size 1.
- ▶ $\mathcal{J}^{1\forall>} \iff$ The strict transitive closure contains an out-dominating set of size 1.
- ▶ $\mathcal{TC} \iff$ The transitive closure is a complete graph.
- ▶ $\mathcal{TC}^> \iff$ The strict transitive closure is a complete graph.
- ▶ $\mathcal{E}^{1\forall} \iff$ The footprint contains a dominating set of size 1 (*a.k.a.* universal vertex).
- ▶ $\mathcal{K} \iff$ The footprint is a complete graph.

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→ Queries can be answered trivially once the intermediate objects are computed!

Exercises: how to compute these objects?

Solutions to the exercises

In all algorithms, the input \mathcal{G} is given as a sequence $\{G_1, \dots, G_k\}$, with $G_i = (V, E_i)$.

Algorithm 1 Computing the footprint

```
1:  $E \leftarrow \emptyset$  // edges of the footprint
2: for all  $G_i \in \mathcal{G}$  do
3:   for all  $e \in E_i$  do
4:      $E \leftarrow E \cup e$ 
5: return  $(V, E)$  // the footprint graph
```

Exercises: how to compute these objects?

Solutions to the exercises

In all algorithms, the input \mathcal{G} is given as a sequence $\{G_1, \dots, G_k\}$, with $G_i = (V, E_i)$.

Algorithm 3 Computing the footprint

```
1:  $E \leftarrow \emptyset$  // edges of the footprint
2: for all  $G_i \in \mathcal{G}$  do
3:   for all  $e \in E_i$  do
4:      $E \leftarrow E \cup e$ 
5: return  $(V, E)$  // the footprint graph
```

Algorithm 4 Computing the strict transitive closure

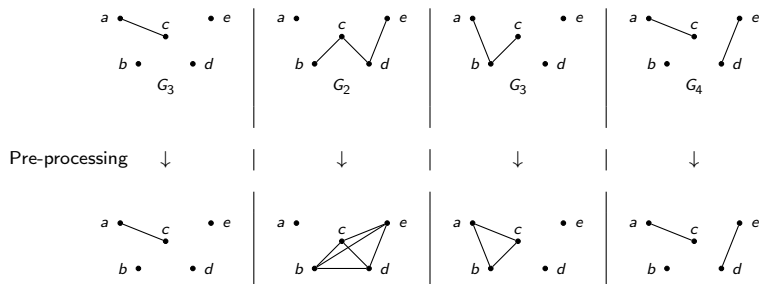
```
1:  $T \leftarrow (V, \emptyset)$  // initial transitive closure
2: for all  $G_i \in \mathcal{G}$  do
3:    $T_{new} \leftarrow copy(T)$ 
4:   for all  $(u, v) \in E_i$  // manipulated as a directed graph do
5:     for all  $w$  such that  $(w, u) \in E(T)$  do
6:        $E(T_{new}) \leftarrow E(T_{new}) \cup (w, v)$ 
7:        $E(T_{new}) \leftarrow E(T_{new}) \cup (u, v)$ 
8: return  $T$ 
```

Solutions to exercises (2)

Algorithm 3 Computing the transitive closure for non-strict journeys

→ 2 steps:

1. Pre-process each graph of the sequence by saturation the connected components



2. Then runs the previous algorithm for *strict* transitive closure on this new sequence.

→ There is an arc in the result if and only if there is a (possibly non-strict) journey in \mathcal{G} .